

# On decision trees, influences, and learning monotone decision trees

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## Abstract

In this note we prove that a monotone boolean function computable by a decision tree of size  $s$  has average sensitivity at most  $\sqrt{\log_2 s}$ . As a consequence we show that monotone functions are learnable to constant accuracy under the uniform distribution in time polynomial in their decision tree size.

## 1 Decision trees

Let  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$  be a boolean function.

**Fourier notions:** Throughout this paper we view  $\{-1, 1\}^n$  as a probability space under the uniform distribution. Recall  $f$ 's *Fourier expansion*,

$$f(x) = \sum_{S \subseteq [n]} \hat{f}(S) \chi_S(x),$$

where  $\chi_S(x) = \prod_{i \in S} x_i$  and  $\hat{f}(S) = \mathbf{E}_x[f(x) \chi_S(x)]$ . We also recall the notions of influence and average sensitivity: The *influence of  $i$  on  $f$*  is  $\text{Inf}_i(f) = \Pr_x[f(x) \neq f(x^{(i)})]$ , where  $x^{(i)}$  denotes  $x$  with the  $i$ th bit flipped; if  $f$  is a monotone function then  $\text{Inf}_i(f) = \hat{f}(\{i\})$ . We shall henceforth write  $\hat{f}(i)$  in place of  $\hat{f}(\{i\})$ . The *average sensitivity of  $f$*  is  $\text{I}(f) = \sum_{i=1}^n \text{Inf}_i(f)$ .

**Decision trees:** Suppose we have a decision tree computing  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$ ; we will always assume (without loss of generality) that no variable appears more than once on any path of the tree. Note that picking a uniformly random input  $x \in \{-1, 1\}^n$  is equivalent to the following two-step procedure: First, pick a uniformly random path  $P$  in the tree by starting at the root and assigning to the variables encountered uniformly at random until a leaf is

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reached. Second, assign uniformly at random to those variables as yet unset. Corresponding to the first step of this process we define a collection of random variables  $P_1, \dots, P_n$  as follows:

$$P_i = \begin{cases} 1 & \text{if the variable } i \text{ is encountered on the random path and } x_i \text{ is chosen to be } 1, \\ -1 & \text{if the variable } i \text{ is encountered on the random path and } x_i \text{ is chosen to be } -1, \\ 0 & \text{if the variable } i \text{ is not encountered on the random path.} \end{cases}$$

For each  $i$  we have  $\mathbf{E}[P_i] = 0$ ; a slight amount of reflection reveals that also  $\mathbf{E}[P_i | P_j] = 0$  for all  $i \neq j$ . Hence while  $P_i$  and  $P_j$  are not independent we do have  $\mathbf{E}[P_i P_j] = 0$  for all  $i \neq j$ . We write  $\Sigma P$  for  $\sum_{i=1}^n P_i$ , the sum of the bit assignments made along the random path  $P$ , and we also write  $\text{len}(P)$  for the length of the random path  $P$ ; another way of expressing  $\text{len}(P)$  is  $\sum_{i=1}^n (P_i)^2$ .

Consider the two-step procedure for choosing  $x \in \{-1, 1\}^n$  at random: first choose  $P$  at random, assigning randomly to the variables on the path; then choose the remaining unset variables uniformly at random. Since the value of  $f(x)$  is fixed after the first step in the procedure, we may denote this value by  $f(P)$ .

**Proposition 1** *Let  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$  be computed by a decision tree with paths  $P$ . Then*

$$\sum_{i=1}^n \hat{f}(i) = \mathbf{E}_P[f(P) \cdot \Sigma P].$$

**Proof:**

$$\begin{aligned} \sum_{i=1}^n \hat{f}(i) &= \sum_{i=1}^n \mathbf{E}_{x \in \{-1, 1\}^n} [f(x) x_i] \\ &= \mathbf{E}_{x \in \{-1, 1\}^n} \left[ f(x) \sum_{i=1}^n x_i \right] \\ &= \mathbf{E}_{P; x_j: P_j=0} \left[ f(P) \left( \sum_{i: P_i \neq 0} x_i + \sum_{j: P_j=0} x_j \right) \right] \\ &= \mathbf{E}_P \left[ f(P) \left( \Sigma P + \mathbf{E}_{x_j: P_j=0} \left[ \sum_{j: P_j=0} x_j \right] \right) \right] \\ &= \mathbf{E}_P [f(P) \cdot \Sigma P]. \end{aligned}$$

The final equality holds since  $\mathbf{E}[x_j | P_j = 0] = 0$  for each  $j$ .  $\square$

**Theorem 1** *Let  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$ .*

1. *If  $f$  is computed by a decision tree of size<sup>1</sup>  $s$  then  $\sum_{i=1}^n \hat{f}(i) \leq \sqrt{\log_2 s}$ .*
2. *If  $f$  is computed by a decision tree of depth  $d$  then  $\sum_{i=1}^n \hat{f}(i) \leq \mathbf{I}(\text{Maj}_d) \sim \sqrt{\frac{2}{\pi}} \sqrt{d} \leq \sqrt{d}$ .*

*If  $f$  is monotone we can replace  $\sum_{i=1}^n \hat{f}(i)$  by  $\mathbf{I}(f)$ .*

**Proof:** Since  $f$  is  $\pm 1$ -valued, from the Proposition it is clear that

$$\sum_{i=1}^n \hat{f}(i) \leq \mathbf{E}_P[|\Sigma P|]$$

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<sup>1</sup>Number of leaves.

with equality iff  $f$  computes the majority of the bits along each of its decision tree paths — i.e.,  $\text{sgn}(\Sigma P)$  ( $f$  may output anything if the bits split evenly.)

In case (1), we proceed as follows:

$$\mathbf{E}_P[|\Sigma P|] \leq \sqrt{\mathbf{E}_P[|\Sigma P|^2]} = \sqrt{\mathbf{E}_P\left[\sum_{i,j=1}^n P_i P_j\right]} = \sqrt{\mathbf{E}_P[\text{len}(P)] + \sum_{i \neq j} \mathbf{E}_P[P_i P_j]} = \sqrt{\mathbf{E}_P[\text{len}(P)]}.$$

(At this point we have proved the upper bound of  $\sqrt{d}$  in case (2).) It remains to show that  $\mathbf{E}_P[\text{len}(P)] \leq \log_2 s$ ; we use induction on  $s$ . The result is obvious when  $s = 2$ ; for larger  $s$ , suppose we have a size- $s$  tree in which the left subtree of the root has size  $s_1$  and the right subtree of the root has size  $s_2$ , with  $s = s_1 + s_2$ . The expected length of a random path in such a tree is 1 plus half the expected length in the left subtree plus half the expected length in the right subtree. By induction this is at most  $1 + \frac{1}{2} \log_2 s_1 + \frac{1}{2} \log_2 s_2 = \log_2(2\sqrt{s_1 s_2}) \leq \log_2(s_1 + s_2) = \log_2 s$  where we have used the AM-GM inequality.

In case (2), we instead note in upper-bounding  $\mathbf{E}_P[|\Sigma P|]$  it doesn't hurt to assume that the tree is a full depth- $d$  tree; this is because if we have a path of depth less than  $d$ , we can extend it redundantly, querying an irrelevant variable — if  $\Sigma P$  for the path was nonzero then  $\mathbf{E}_P[|\Sigma P|]$  is unchanged, if  $\Sigma P$  for the path was zero then  $\mathbf{E}_P[|\Sigma P|]$  will increase. Now note that  $\mathbf{E}_P[|\Sigma P|]$  does not depend on the names of the variables labeling the nodes of the tree; hence we may assume that all nodes at level  $\ell$  read  $x_\ell$ , for  $\ell = 1 \dots d$ . But now equality in  $\sum_{i=1}^n \hat{f}(i) \leq \mathbf{E}_P[|\Sigma P|]$  occurs if the decision tree computes  $\text{Maj}_d$ , as claimed. The asymptotic formula  $\mathbf{I}(\text{Maj}_d) = (1 + o(1))\sqrt{\frac{2}{\pi}}\sqrt{d}$  is well known.  $\square$

**Remarks:**

1. In the case of monotone functions with depth- $d$  decision trees, Theorem 1 generalizes the well-known edge-isoperimetric inequality on the discrete  $n$ -cube, which says that for monotone  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$ ,  $\mathbf{I}(f) \leq \mathbf{I}(\text{Maj}_n)$ .
2. We conjecture that if  $s = s(d)$  is the minimal size of a decision tree computing  $\text{Maj}_d$ , then every function  $f$  computable by a decision tree of size  $s$  has  $\sum_{i=1}^n \hat{f}(i) \leq \sum_{i=1}^n \widehat{\text{Maj}}_d(i)$ .

## 2 Learning monotone decision trees

The following result is immediate from inspecting the proof of Friedgut's '98 theorem about functions with low average sensitivity [Fri98]:

**Theorem 2** *Let  $f: \{-1, 1\}^n \rightarrow \{-1, 1\}$ ,  $\epsilon > 0$ ,  $t = 2\mathbf{I}(f)/\epsilon$ , and  $J = \{i : \text{Inf}_i(f) \geq t3^{-t}\}$ . Then  $|J| \leq 3^t$ , and furthermore*

$$\sum_{S: S \subseteq J, |S| \leq t} \hat{f}(S)^2 \geq 1 - \epsilon.$$

Combining Theorems 1 and 2 with the idea behind the monotone DNF learning algorithm of [Ser01], we get the following uniform distribution algorithm for learning monotone functions in time polynomial in their decision tree size:

**Theorem 3** *The class of monotone functions can be learned under the uniform distribution to accuracy  $\epsilon$  (with confidence  $1 - \delta$ ) in time  $s^{O(1/\epsilon^2)} \cdot \text{poly}(n) \cdot \log(1/\delta)$ , where  $s$  represents decision tree size.*

**Proof:** Let  $f$  be the unknown monotone function to be learned. We may assume that the algorithm knows  $s$ , the decision tree size of  $f$ , by a standard doubling argument. From Theorem 1 we know that  $I(f) \leq \sqrt{\log_2 s}$ ; let  $t = 2\sqrt{\log_2 s}/\epsilon$ . Since  $f$  is monotone, its influences are equal to its degree-one Fourier coefficients and thus can be accurately estimated from uniformly random samples. The algorithm first determines the set  $J = \{i : \text{Inf}_i(f) \geq t3^{-t}\}$ . It then estimates all Fourier coefficients  $\hat{f}(S)$  such that  $|S| \leq t$  and  $S \subseteq J$ . By Theorem 2 this gives the algorithm all but  $\epsilon$  of  $f$ 's spectrum; it is well known that this is sufficient for learning  $f$  to accuracy  $\epsilon$ . To conclude we note that up to the  $\text{poly}(n) \cdot \log(1/\delta)$  the running time is dominated by the number of Fourier coefficients estimated, which is at most  $|J|^t = 3^{t^2} = s^{O(1/\epsilon^2)}$ .  $\square$

## References

- [Fri98] E. Friedgut. Boolean functions with low average sensitivity depend on few coordinates. *Combinatorica*, 18(1):474–483, 1998.
- [Ser01] R. Servedio. On learning monotone DNF under product distributions. *14th Ann. Conference on Comp. Learning Theory*, 558–573, 2001.